

# MF40 ER

## Electronic Return (SuperCap) Butterfly Valve Actuator Modulating and Two-Position Control, 40 Nm



### Product Description

The MF40ER is a robust, reliable rotary actuator for the control of the VF208W DN125-200 butterfly valves.

The MF40ER actuators utilize super capacitor technology for driving the valve either closed or open in the event of power failure.

These actuators do not require linkage kits, providing a quick and simple installation.

- 24 Vac or Vdc Power supply
- 2...10 V Position Feedback
- Long Life SuperCaps

The actuator is overload-proof, requiring no limit switches and automatically stopping when the end point is reached.

### Specifications

Nominal Torque	Min. 40 Nm
Supply Voltage Range	
AC	19.2...28.8 V 50...60 Hz
DC	21.6...28.8 V
Running Time	
Motor Driven	150 s/90°
Capacitor Driven	35 s/90°
Control Signal	
MF40ER-24M	
Range of Operation (X)	2...10 Vdc
Input Resistance	100 kΩ
Position Feedback (Y)	2-10 Vdc, max 0.5 mA
Position Accuracy	+/- 5%
Electronic Return Position	0 (100% of max. angle or rotation (POP dial))
Direction of Rotation	
Motor (mod.)	Reversible with Switch 0/1
Electronic Return (SuperCap) position	0 ... 100% (any position between, as set by POP dial)
Angle of Rotation	Max. 90°, limited both ends, adjustable end stops
Position Indication	Mechanical
Electrical Connection	
Cable	4 x 0.75 mm <sup>2</sup>
Length	1.0 m

### Features

- Straightforward direct mounting onto the butterfly valve, using only two bolts. The mounting position in relation to the butterfly valve can be selected in 90° steps. There is no internal mechanical spring, and the normally open or closed functionality in the event of a power failure is governed by the POP (power off positioning) dial.
- Manual operation of the valve is possible using the actuator hand crank. The actuator drives to the control signal position with electrical supply or to the POP position when power is not present.
- All units have an adjustable angle of rotation up to 90° with mechanical limit stops adjustable from each end.
- Super capacitor technology drives the actuator to a pre-defined position in the event of power interruption. Super capacitors have advantage over traditional spring return actuators as the motor does not need to overcome mechanical spring resistance. This increases the torque output in the actuator and drives butterfly valve sizes up to DN200.

Power consumption	
Operation	11 W @ nominal torque
At Rest	<3 W
Wire Sizing	≤21 VA
Environment	
Operating Temperature	0 °C...+ 50 °C
Media Temperature Range	-20 °C...+ 100 °C
Storage (Non operation)	-40 °C...+ 80 °C
Ambient Humidity	95% r.h. Non-condensing
Sound Power Level, Motor	≤52 dB
Electronic Return (SuperCap Driven)	≤61 dB
Weight	approx. 2.8 kg
Safety	
Protection Class	III Safety Extra low Voltage / UL class 2 Supply
Degree of Protection	IP54 NEMA2, UL Enclosure Type 2
Maintenance	Maintenance free
Control Pollution Degree	3
Mode of Operation	
Type 1.AA	
Rated Impulse Voltage	0.8 kV
Standards Conformity	
EMC	CE according to 2004/108/EC
Certification	cULus to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1:02, IEC/EN 60730-1 and IEC/EN 60730-2-14

## Available Products

Part Number	Type Designation	Power Supply		Power Consumption			Control Signal	Cable Size
		Vac	Vdc	Operation	Rest	Wire Sizing		
MF40ER-24M	MF40ER-24M 1M54 00	19.2 to 28.8	21.6 to 28.8	11 W	3 W	21 VA	2-10 Vdc Modulating	4 x 0.75 mm <sup>2</sup>
MF40ER-24T	MF40ER-24T 15M54 00						2 position	4 x 0.75 mm <sup>2</sup>

## Mode of Operation

The modulating actuator is positioned and controlled with a standard 2...10 Vdc control signal. If the supply voltage is interrupted the valve is returned by the electrical charge of the internal super capacitors to the position indicated by the POP dial.

The direction of rotation switch changes the running direction of the actuator against the control signal. The direction of rotation switch has no influence on the power off position as set by the POP switch.

The two-position actuator (MF40ER-24T) is driven fully on by a 24 Vac or Vdc supply and is returned by the super capacitors when the 24 V supply is switched off.

## Power Off Position (POP) setting

The Power Off Position (POP) is an electronic position return feature in the MF40ER actuator.

The position can be determined from the POP setting dial on the top of the actuator.

The switch always refers to an angle of rotation of 90° and does not take into account any retroactively adjusted mechanical end stops.

In the event of a power supply interruption, the actuator will move into the selected power off position, initiating after a preset bridging time (PF) of 2 sec.

## Operating Controls and indicators

Power Off Position (POP)

1

2

3

4

6

7

LED display	Meaning/Function
8 green	Operation OK / without fault
Illuminated	POP-Function active
Blinking	- Not in Operation - Pre-charging time SuperCap
Off	

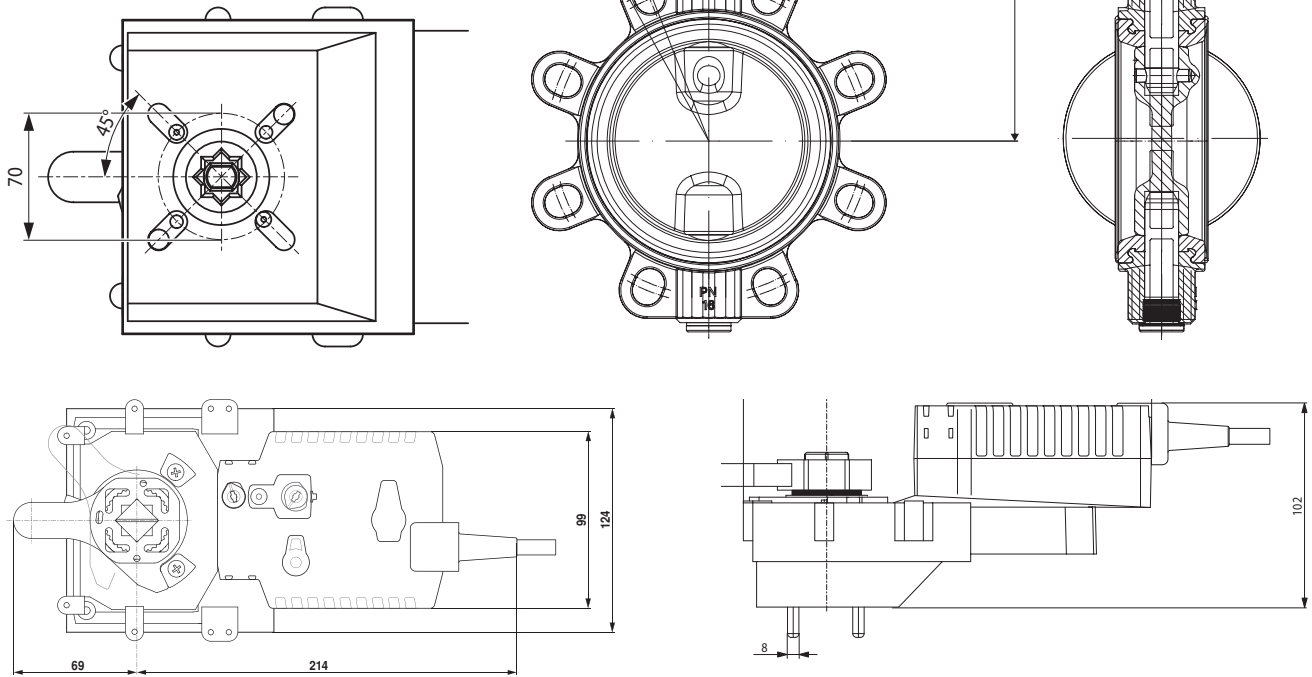
0.5 0.1 NO 0.9 NC	→	A – AB 100%
0.5 0.1 NO 0.9 NC	→	A – AB 0%
0.5 0.1 NO 0.9 NC	→	A – AB 0... 100%

## Dimensions (mm)

DN	125	150	200
H1	243	309	343
P1	69		
P2	166		
P3	134		

Dimensions in mm

Valve dimensions can be found on the respective valve data sheets.



## Safety Notes




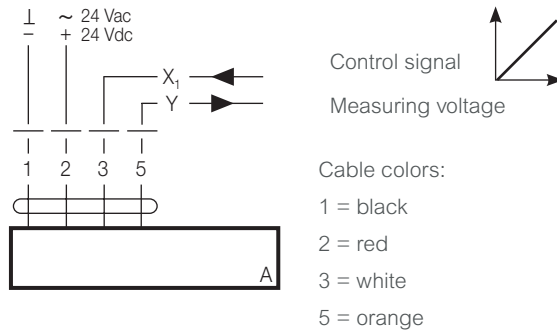
- The actuator must not be used outside the specified field of application.
- It may only be installed by suitably trained or supervised personnel. Any legal regulations or other regulation issued by authorities must be observed during installation.
- The switch for changing the direction of rotation must only be operated by authorised personnel. In particular, the direction of rotation must not be reversed in a frost protection circuit.
- The actuator may only be opened at the manufacturer's site. It does not contain any serviceable or replaceable parts by the user.
- The cable and connector must not be removed from the device.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

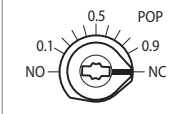
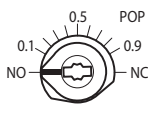
## Wiring Diagrams

### MF40ER-24M

Note

Connect via safety isolation transformer. 

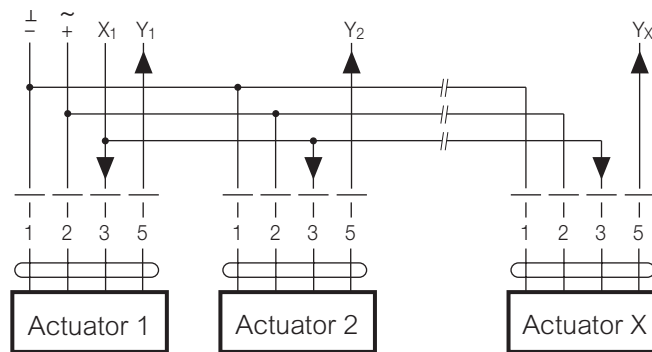


NC	NO
A-AB=0%	A-AB=100%
	

## Parallel Operation

Notes

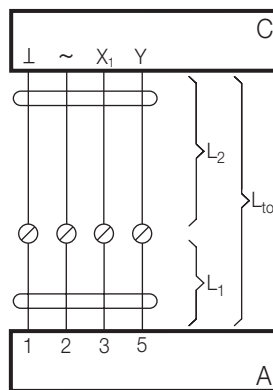
- A maximum of eight actuators can be connected in parallel.
- Parallel operation is permitted only for separated axes.
- It is imperative that the performance data is observed with parallel operation.



## Cable Lengths

Note

When several actuators are connected in parallel, the maximum cable length must be divided by the number of actuators.



A = Actuator

C = Control unit

$L_1$  = Attached connecting cable, 1 m (4 x 0,75 mm<sup>2</sup>)

$L_2$  = Customer cable

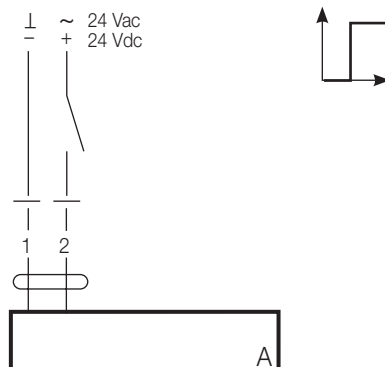
$L_{tot}$  = Maximum cable length

Cross-section $L_2$	Max. Cable length $L_{tot} = L_1 + L_2$		Example for Vdc
	Vac	Vdc	
0,75 mm <sup>2</sup>	≤40 m	≤20 m	1 m ( $L_1$ ) + 19 m ( $L_2$ )
1,00 mm <sup>2</sup>	≤50 m	≤30 m	1 m ( $L_1$ ) + 29 m ( $L_2$ )
1,50 mm <sup>2</sup>	≤80 m	≤45 m	1 m ( $L_1$ ) + 44 m ( $L_2$ )
2,50 mm <sup>2</sup>	≤130 m	≤80 m	1 m ( $L_1$ ) + 79 m ( $L_2$ )

### MF40ER-24T

Note

Connect via safety isolation transformer.



NC	NO
A-AB=0%	A-AB=100%
